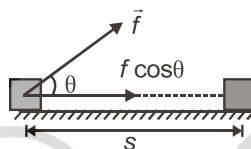


Chapter 4

Work, Energy and Power

CONCEPT OF WORK

$$\begin{aligned} W &= \vec{f} \cdot \vec{s} \quad (\vec{s} = \vec{s}_2 - \vec{s}_1) \\ &= fs \cos \theta \\ &= s (f \cos \theta) \end{aligned}$$



KINETIC ENERGY

$$\text{K.E.} = \frac{1}{2}mv^2 = \frac{p^2}{2m}$$

WORK-ENERGY THEOREM

$$W_{\text{Total}} = \Delta \text{K.E.}$$

or

$$W_{\text{ext.}} + W_{\text{int.}} = \Delta \text{K.E.}$$

Work Done by Spring Force

$$W = - \int_{x_1}^{x_2} kx dx = -\frac{1}{2}k(x_2^2 - x_1^2)$$

when $x_2 > x_1$, $W < 0$

when $x_2 < x_1$, $W > 0$

COLLISION

One dimension

$$\begin{array}{ccc} \xrightarrow{u_1} & \xrightarrow{u_2} & \\ \textcircled{m_1} & \textcircled{m_2} & \Rightarrow \quad \textcircled{m_1} \quad \textcircled{m_2} \\ \xrightarrow{v_1} & \xrightarrow{v_2} & \end{array} \quad (u_1 > u_2 \text{ and } v_2 > v_1)$$

$$\Delta \text{KE} = \frac{1}{2} \frac{m_1 m_2}{m_1 + m_2} (u_1 - u_2)^2 (1 - e^2)$$

Following are the important cases

1. Elastic collision $e = 1$

$$v_2 - v_1 = u_1 - u_2$$

$$v_1 = \frac{m_1 - m_2}{m_1 + m_2} u_1 + \frac{2m_2 u_2}{m_1 + m_2}$$

$$v_2 = \frac{m_2 - m_1}{m_2 + m_1} u_2 + \frac{2m_1 u_1}{m_2 + m_1}$$

$$\Delta KE = 0 \Rightarrow \text{Final KE} = \text{Initial KE}$$

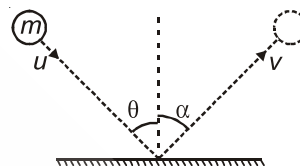
2. Coefficient of restitution $= e$

$$u \sin \theta = v \sin \alpha \quad \dots(1)$$

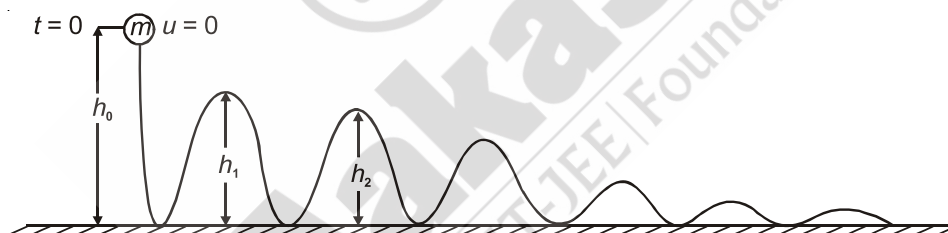
$$eu \cos \theta = v \cos \alpha \quad \dots(2)$$

$$\Rightarrow v = u \sqrt{\sin^2 \theta + e^2 \cos^2 \theta}$$

$$\tan \alpha = \frac{\tan \theta}{e} \quad (\text{i.e. } \alpha > \theta)$$



3. A ball of mass m is dropped from a height h_0 on an inelastic floor.



The coefficient of restitution $= e$

(a) Maximum height after n^{th} bounce is $h_n = e^{2n} h_0$

(b) Speed of rebound after n^{th} bounce $= e^n \sqrt{2gh_0}$

(c) Total distance travelled before the body comes to rest

$$= h_0 \left[\frac{1 + e^2}{1 - e^2} \right]$$

(d) The time after which the body comes to rest

$$= \sqrt{\frac{2h_0}{g}} \cdot \left[\frac{1 + e}{1 - e} \right]$$

(e) Average force exerted on the ground is mg

(f) Displacement of ball when it stops is h_0

4. Oblique elastic collision

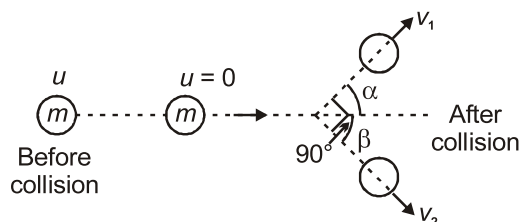
A body of mass m collides with a stationary body of same mass.

$$(a) \quad \alpha + \beta = \frac{\pi}{2} \quad \dots(1)$$

$$(b) \quad v_1 \cos \alpha + v_2 \cos \beta = u \quad \dots(2)$$

$$(c) \quad v_1 \sin \alpha = v_2 \sin \beta \quad \dots(3)$$

$$(d) \quad u^2 = v_1^2 + v_2^2 \quad \dots(4)$$

**MOTION IN A VERTICAL CIRCLE**

A particle of mass m is tied to a string of length l whose other end is fixed. The particle can revolve about O in a vertical circle. When it is at position L (lowest point), it is given a speed V_L horizontal. Following results are useful in describing its motion.

$$1. \quad a_T = g \sin \theta \quad \dots(1)$$

$$2. \quad a_C = \frac{T_p - mg \cos \theta}{m} = \frac{v_p^2}{l}$$

$$3. \quad T_p = \frac{mv_p^2}{l} + mg \cos \theta \quad \dots(2)$$

$$4. \quad T_L = mg + \frac{mv_L^2}{l}$$

$$5. \quad v_L \leq \sqrt{2gl}, \text{ it oscillates between } M \text{ and } M'$$

$$6. \quad \sqrt{2gl} < v_L < \sqrt{5gl}, \text{ it will leave the circular path somewhere between } M' \text{ and } H.$$

$$7. \quad \text{When } v_L \geq \sqrt{5gl}, \text{ it completes vertical circle (Also } v_H \geq \sqrt{gl} \text{)}$$

$$8. \quad T_H = -mg + \frac{mv_H^2}{l}$$

$$9. \quad T_L - T_H = 6mg \text{ (always)}$$

